

# TTY layer – here lies daemons

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# The TTY demystified

<https://www.linusakesson.net/programming/tty/>



“Good luck fixing the tty layer” – Thomas Gleixner

<https://lwn.net/Articles/938236/>

tty layer is why we are here

# tty vs. line disciplines vs. serial port

# tty vs. line disciplines vs. serial port

- › We are going to ignore consoles, they are “magic”

# tty

- › Char device
  - userspace open/read/write/ioctl/close
- › Assign a line discipline to a tty
- › ioctls are line-discipline-specific

# Line discipline

- › Protocol to be talked on the tty
- › ~20 different ones
  - Normal (n\_tty), gps, slip, CAN, ham radio, ppp, videophone modem control, etc...
  - “internal serial port connection”
- › Works for any tty connection / any tty device

# “serial port” – tty driver

- › “hardware” to look like a tty device
- › serial port subsystem (uarts)
- › USB-serial subsystem (fake and real uarts)
- › ptys (pseudo-terminals)
- › ISDN devices
- › s390 devices
- › ~40 different ones

# ttyprintk.c

- › Userspace write to show up in kernel log
- › 200 lines of code
- › One way “userspace → kernel”
- › Good example codebase

# `struct tty_struct`

- › 1 kref
- › 4 mutexes
  - One emulates old BKL
- › 1 rw\_semaphore
- › 1 spinlock

# **struct tty\_struct – cont.**

- › 2 wait queues
- › 2 work structs

## **struct tty\_struct – cont.**

- › 2 internal structs
  - Each have a spinlock
  - Properly padded for 64bit store on ALPHA

## struct tty\_struct – cont.

```
/* size: 656, cachelines: 11, members: 37 */  
/* sum members: 654, holes: 1, sum holes: 2 */  
/* forced alignments: 2 */  
/* last cacheline: 16 bytes */
```

# `struct tty_driver`

- › 36 function callbacks

# `struct tty_port`

- › 1 spinlock
- › 2 mutexes
- › 1 kref
- › 2 wait queues

# `struct uart_port`

- › 27 function callbacks
- › 1 spinlock
- › 1 global spinlock for any serial line change

# `struct usb_serial_driver`

- › 38 function callbacks

# **struct usb\_serial\_device**

- › 1 **struct tty\_port**
- › 1 **spinlock**
- › 1 **struct device**

# tty\_write()

- › Can be called in lots of odd ways
  - console magic
- › Iterator fun!

```
static ssize_t tty_write(struct kiocb *, struct iov_iter *);
```

# `iterator_tty_write()`

- › Start of the real work
- › `tty_write_lock()`

# tty\_write\_lock()

- › mutex\_trylock()
- › Failed? mutex\_lock\_interruptible()
- › Failed? Return restart error

# iterator\_tty\_write()

- › Check buffer size
  - Too small – allocate more data!
    - `kvmalloc()` / `kvfree()`
    - Non-deterministic mess #1

# iterator\_tty\_write()

- › copy\_from\_iter()
- › Pass data to line discipline

# iterator\_tty\_write()

```
/* FIXME! Have Al check this! */

if (ret != size)

    iov_iter_revert(from, size-ret);
```

# iterator\_tty\_write()

```
/* FIXME! Have Al check this! */

if (ret != size)
    iov_iter_revert(from, size-ret);

...
if (signal_pending(current))
    break;
cond_resched();
```

## iterator\_tty\_write()

- › Keep looping until add data send to lower layer

# `iterator_tty_write()`

› `tty_update_time()`

# tty\_update\_time()

- › ktime\_get\_real\_seconds()
- › Grab a spinlock
- › Iterate over all open file descriptors for the tty
- › Change the timestamp if within 8 seconds
- › Release spinlock

# iterator\_tty\_write()

› tty\_write\_unlock()

## n\_tty write

- › Loop over all data given to us:
- › down\_read()
- › Process pending echo chars (how many?)

## n\_tty write

- › Loop over all data given to us:
- › down\_read()
- › Process pending echo chars (how many?)
  - Non-deterministic mess #2!

## n\_tty write

- › Loop over all data given to us:
- › down\_read()
- › Process pending echo chars (how many?)
- › Add wait queue
- › Pending signals?
  - abort

## n\_tty write

- › Process unknown amount of output blocks

## n\_tty write

- › Process unknown amount of output blocks
  - Non deterministic mess #3

# n\_tty write

- › Process unknown amount of output blocks
- › `mutex_lock()`
  - tty driver write call
- › `mutex_unlock()`
- › `up_read()`

# n\_tty write

- › Wake up waitqueue
- › down\_read()
- › Back to top of loop

## n\_tty write

- › Wake up waitqueue
- › down\_read()
- › Back to top of loop if more data to send
- › Remove wait queue
- › up\_read()

# tty driver write

- › Serial port write

# Serial port write

- › `uart_port_lock()`
- › `memcpy()` data to local buffer
  - Only `PAGE_SIZE` big
- › UART send

# UART send

- › pm\_runtime\_get()
- › 8250 send

# 8250 send

- › Tweak pm flags again
- › Read LSR from hardware

# 8250 send

- › Tweak pm flags again
- › Read LSR from hardware
  - Non-deterministic mess #4

# 8250 send

- › Tweak pm flags again
- › Read LSR from hardware
- › Write bytes to uart (one at a time? DMA?)

# 8250 send

- › Tweak pm flags again
- › Read LSR from hardware
- › Write bytes to uart (one at a time? DMA?)
  - Non-deterministic mess #X

# 8250 send

- › Tweak pm flags again
- › Read LSR from hardware
- › Write bytes to uart (one at a time? DMA?)
- › UART port unlock

# Recieve data from hardware

- › `tty_insert_flip_char()` / `tty_insert_flip_string()`
- › `tty_flip_buffer_push()`

# `tty_insert_flip_*`()

- › Have enough memory?
  - No, allocate more (can not fail, wait forever)
  - Max buffer ~1Mb
  - No driver checks this, if no readers are there, data will drop on the floor
- › Loop to copy all data to buffer
  - TTY\_BUFFER\_PAGE

# tty\_flip\_buffer\_push()

- › smb\_store\_release()
- › Wake up workqueue

**Sometime later**

## tty\_flip\_buffer\_push() workqueue

- › Buffer lock (one per port)
- › atomic\_read()
- › smb\_load\_acquire() X 2
- › Line discipline receive\_buff()
- › cond\_resched() if needed
- › Loop until all data flushed
- › Buffer unlock

# n\_tty receive\_buff()

- › down\_read()
- › smp\_load\_acquire()
- › Copy data into ldisc buffer
- › smb\_load\_release()
- › Wake up ldisc read waitqueue
- › up\_read()

# tty\_read()

- › No locks!
- › 64 bytes on the stack
- › Line discipline read()
- › copy\_to\_user\_buffer()
- › memset() stack buffer to 0

# n\_tty read()

- › down\_read()
- › smb\_load\_aquire()
- › memcpy() from flip buffer to stack buffer
- › Adjust pointers
- › tty\_audit\_add\_data()
- › up\_read() sometime later...

# `tty_audit_add_data()`

- › Allocate buffer

# tty\_audit\_add\_data()

- › Allocate buffer
  - Can sleep!

# `tty_audit_add_data()`

- › Allocate buffer
- › `mutex_lock()`
- › `memcpy()`
- › Write to audit log

# tty\_audit\_add\_data()

- › Allocate buffer
- › mutex\_lock()
- › memcpy()
- › Write to audit log
  - We don't have enough time....

# `tty_audit_add_data()`

- › Allocate buffer
- › `mutex_lock()`
- › `memcpy()`
- › Write to audit log
- › `mutex_unlock()`

# tty layer – the bad

- › It's complicated
- › Too flexible
- › Too many entry/exit points
- › Lots of opportunities to sleep
- › Non-deterministic in so many places
- › UARTS are complex and dumb

# tty layer – the good

- › It is fast
- › It is flexible
- › It supports all hardware
- › It is why Linux has succeeded

# tty layer – how to fix it

- › printk changes to add “simple” console callbacks

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- › Don't enable auditing!

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- › Don’t enable auditing!
- › Don’t use it!

# tty layer – how to fix it

- › printk changes to add “simple” console callbacks  
<https://lwn.net/Articles/909980/>
- › Call it from non-realtime userspace tasks
- › Don't enable auditing!
- › Don't use it!
  - raw\_uart.c
    - read/write ringbuffer, no line control changes

# tty layer – how to fix it

- › patches welcome!

# tty layer – leave it alone



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