

Running FOSS on a Thermal Camera

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Collabora

Who am I?



- ▶ Kernel Engineer at Collabora
- ▶ Maintainer of kernel's power-supply subsystem
- ▶ Debian Developer
- ▶ Living in Oldenburg, Germany
 - ▶ Co-Founder of the local hackerspace
 - ▶ Deputy Lead of the Fire Brigade Diver Squad

What's a thermal camera?

- ▶ Camera for infrared (8-14 μ m) instead of visible spectrum (380nm - 750nm)
- ▶ Usually low resolution (Kilopixel instead of Megapixel)
- ▶ Usually low speed
- ▶ Best known vendor for sensors is FLIR Systems
- ▶ US export restrictions
 - ▶ 9 FPS, 17 μ m pixel pitch (~640x480)

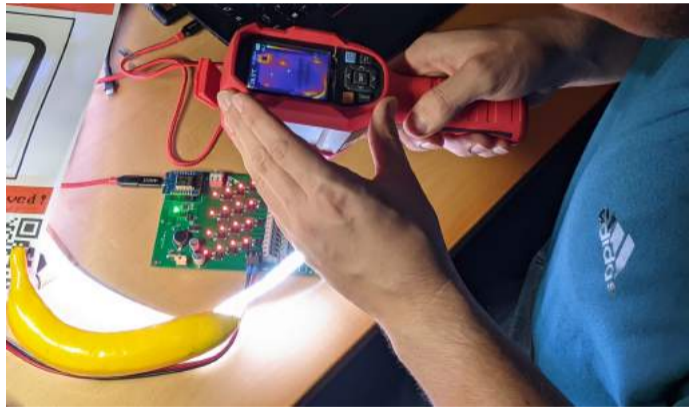
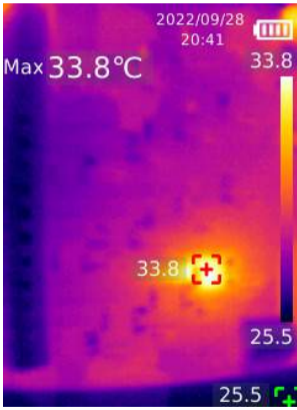
What are they used for?

- ▶ target search (hence the export restrictions)
- ▶ search and rescue
 - ▶ finding hot spots after a fire
 - ▶ finding persons, especially in winter
- ▶ night vision & surveillance
- ▶ building inspection
- ▶ electronic fault search
- ▶ ...

UNI-T UTi260B

- ▶ Thermal Cameras used to be quite expensive or super low resolution
- ▶ Found a 256x192 camera with 25 FPS for ~300€
- ▶ For reference, the model we use at the fire brigade costs 2000€ and has roughly the same specs

PCB fault



Open First

Software is quite bad

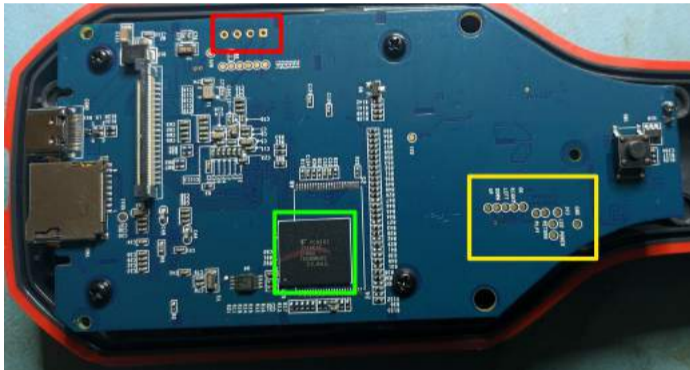
- ▶ Needs roughly 30 seconds to boot
- ▶ Taking an image keeps the overlay (like a screenshot)
- ▶ System is a bit laggy
- ▶ Colormap automatically rescales and cannot be locked

Void warranty - Let's look inside



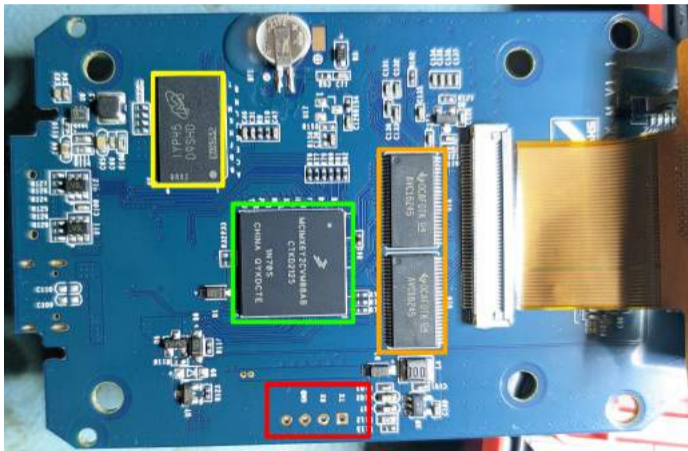
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Hardware



- ▶ Green
 - ▶ THGBMNG5 D1LBAIL
 - ▶ 4GB eMMC
- ▶ Yellow
 - ▶ Debug Pads
 - ▶ Plaintext Labels :)
- ▶ Red
 - ▶ unpopulated connector
 - ▶ UART?

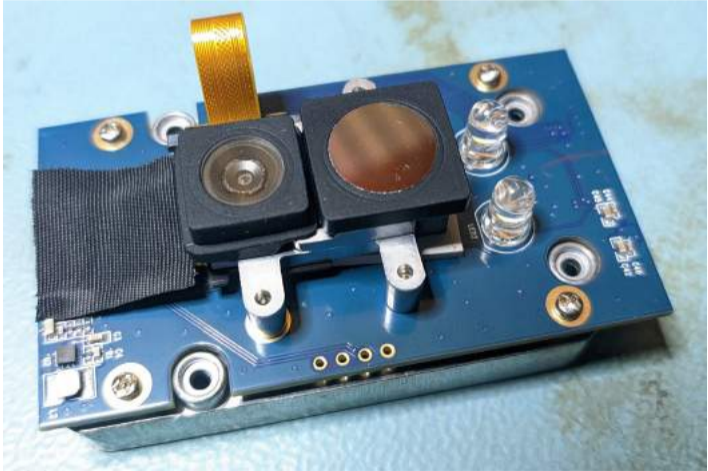
Hardware



- ▶ Yellow
 - ▶ D9SHD
 - ▶ Micron 4Gb DDR3-1866
- ▶ Orange
 - ▶ AVC16245
 - ▶ TI bus transceiver
- ▶ Green
 - ▶ MCIMX6Y2CVM08AB
 - ▶ NXP i.MX6ULL
- ▶ Red
 - ▶ GND / RX / TX
 - ▶ UART ?

Open First

Camera Module Hardware



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Hardware Hacking



- ▶ Solder in Connector
- ▶ Power on the system
- ▶ Measure Voltages
 - ▶ usually one of 1.8V, 3.3V or 5V
- ▶ Use matching USB serial adapter
 - ▶ 5V on 1.8V pin breaks the pads and or device!

Open First

Everything is better with Bluetooth



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UART output

U-Boot 2015.04 (Mar 25 2020 - 13:40:37)

CPU: Freescale i.MX6ULL rev1.1 at 396 MHz

CPU: Temperature 36 C

Reset cause: POR

Board: MX6UL 14x14 EVK

I2C: ready

DRAM: 512 MiB

MMC: FSL_SDHC: 0, FSL_SDHC: 1

[...]

Starting kernel ...

[0.000000] Booting Linux on physical CPU 0x0

[0.000000] Linux version 3.14.38-6UL_ga (ubuntu@ubuntu) (gcc version 4.6.2 20110630 (prerelease))

[0.000000] CPU: ARMv7 Processor [410fc075] revision 5 (ARMv7), cr=10c53c7d

[0.000000] CPU: PIPT / VIPT nonaliasing data cache, VIPT aliasing instruction cache

[0.000000] Machine model: Freescale i.MX6 UltraLite 14x14 EVK Board

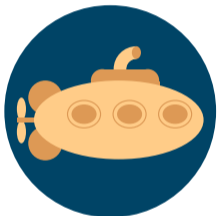
[...]

UNIT login:

Investigating hardware

- ▶ booted into existing system with `init=/bin/sh`
- ▶ change root password
- ▶ reboot
- ▶ investigate running system
 - ▶ there are two V4L2 devices
 - ▶ one is i.MX6ULL CSI
 - ▶ one is USB Video Class
 - ▶ there is one binary running
 - ▶ unstripped, linked against Qt and OpenCV
 - ▶ there is basically no optimization
 - ▶ system has ALSA, Can, Network, Bluetooth, ...
- ▶ let's switch to our own setup

U-Boot



U-Boot

```
=> printenv bootcmd
bootcmd=
    if mmc rescan; then
        if run loadbootscript; then
            run bootscript;
        else
            if test ${bootdev} = sd1; then
                echo update firmware.....;
                run update_from_sd;
            else
                echo mmc boot.....;
                if run loadimage;
                    then run mmcboot;
                    else run netboot;
                fi;
            fi;
        fi;
    else
        run netboot;
    fi;
```


U-Boot

- ▶ loadbootscript tries to load boot.scr from eMMC...
- ▶ ... but that's not used by UNI-T
- ▶ modify that to check for boot.scr on SD card
- ▶ TODO: find an exploit in original FW that can do this

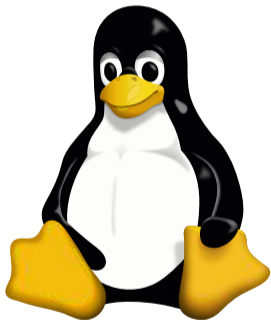
```
=> printenv loadbootscript
loadbootscript=fatload mmc ${mmcdev}:${mmcpart} ${loadaddr} ${script};
=> printenv mmcdev
mmcdev=1
=> printenv mmcpart
mmcpart=1
=> setenv loadbootscript 'fatload mmc 0:1 ${loadaddr} ${script};'
=> saveenv
```

Prepare SD card

- ▶ Create FAT partition for U-Boot with boot.scr
- ▶

```
echo "Executing boot.scr from MicroSD card..."  
setenv mmcroot '/dev/mmcblk0p2 rootwait rw console=ttyMxc0,115200n8'  
setenv fdt_file imx6ull-uti260b.dtb  
setenv mmcdev 0  
run loadimage  
run loadfdt  
run mmcargs  
bootz ${loadaddr} - ${fdt_addr}
```
- ▶ `debootstrap -arch=armhf testing /mnt/sdcard`

Kernel & DT



- ▶ i.MX6ULL is supported mainline
 - ▶ `make imx_v6_v7_defconfig`
 - ▶ `sed -i "s/=m/=y/g" .config`
 - ▶ (optionally) go through config and remove unnecessary stuff
 - ▶ e.g. Bluetooth and WLAN
 - ▶ my zImage went down from 40MB to 3.6MB
 - ▶ faster boot, faster copy-to-device => faster test cycles
- ▶ start with very small device DT
 - ▶ Model
 - ▶ UART
 - ▶ Memory
 - ▶ SD card

Watchdog

- ▶ device has no hard reset button
 - ▶ option 1: wait for battery to be empty
 - ▶ option 2: open device and disconnect battery
 - ▶ option 3: make sure device never hangs
 - ▶ option 4: modify hardware
 - ▶ (e.g. add normally closed reed switch)

Improving hardware support

- ▶ Original system leaks information
 - ▶ DT blob can be decompiled
 - ▶ `dtc -I dtb -O dts imx6ul-14x14-evk.dtb > dump.dts`
 - ▶ GPIOs can be investigated in sysfs
 - ▶ some of them might not be GPIOs in mainline
 - ▶ e.g. `<&gpio2 2>` controls the flashlight LED (`leds-gpio`)
 - ▶ e.g. `<&gpio2 3>` is the power button (`gpio-keys`)
- ▶ Bootloader also leaks information
 - ▶ Original Linux just configures LCDIF
 - ▶ But U-Boot states `LCD st7789v init successfully!`
 - ▶ That's an SPI controller
 - ▶ bootloader pinmux reveals the right SPI port

USB

- ▶ The device has a USB-C port
 - ▶ Used for charging, but also supports USB gadget mode
 - ▶ Original FW offers to screencast via USB UVC
- ▶ Add bootscript to enable USB gadget mode with ECM
 - ▶ Device will provide itself as ethernet device
 - ▶ One can SSH to it

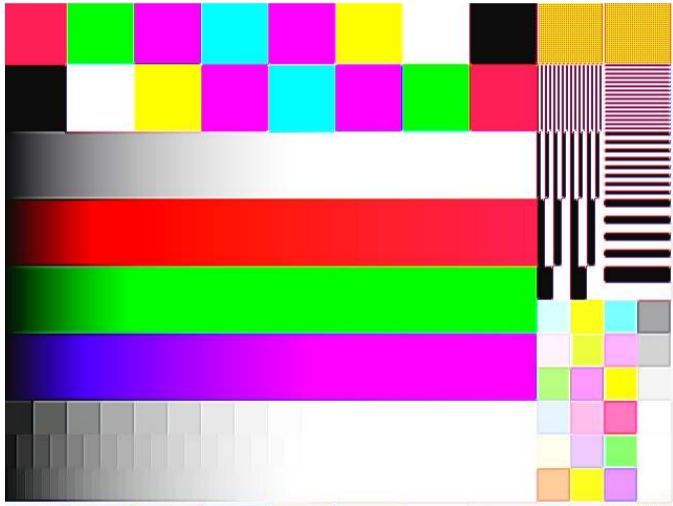
Hardware that did not work OOTB

- ▶ Battery Handling (6.5)
 - ▶ Charger is TP5000 (found on PCB)
 - ▶ Has a GPIO to report that a charger is connected
 - ▶ There's a second GPIO to report that charging is done
 - ▶ For Battery only Voltage is available via ADC
 - ▶ there are existing `gpio-charger` and `adc-battery` drivers
 - ▶ <https://lore.kernel.org/all/20230317225707.1552512-1-sre@kernel.org/>
- ▶ Display Driver (6.6)
 - ▶ Labeled "Inanbo T28CP45TN89 v17"
 - ▶ Tried to use existing `ST7789V` driver
 - ▶ flipped some bits and got it working
 - ▶ <https://lore.kernel.org/all/20230714013756.1546769-1-sre@kernel.org/>
- ▶ Cameras

Optical Camera

- ▶ i.MX6ULL CSI driver recently moved from staging
- ▶ Optical sensor is Galaxycore GC0308 (640x480 / 0.3MP)
 - ▶ No mainline driver :(
 - ▶ datasheet is public, but hard to read
 - ▶ sensor has some ISP functionality (like auto gain)
 - ▶ there's a bunch of low quality out of tree drivers
 - ▶ many configurations break the i.MX6ULL CSI driver
 - ▶ still WIP

Optical Camera



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Optical Camera



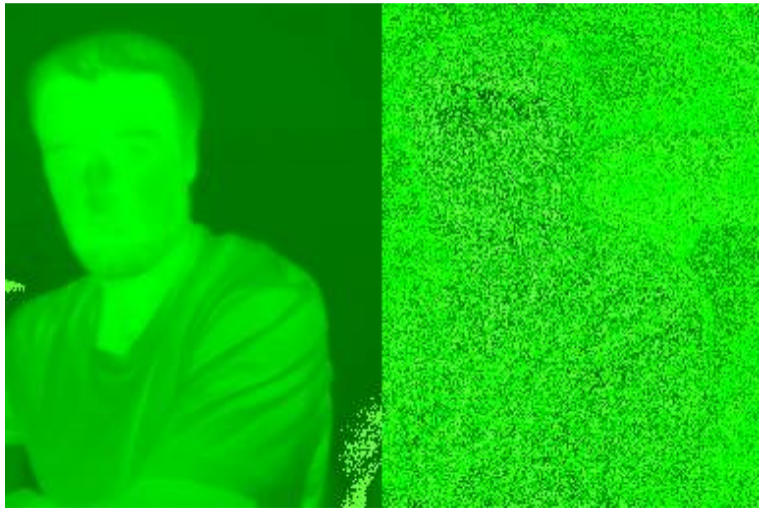
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Thermal Camera

- ▶ Exposes UVC
- ▶ It lies about data format
- ▶ In addition to UVC also takes vendor USB control commands
 - ▶ e.g. high gain (up to 100°C) VS low gain (up to 550 °C)

```
gst-launch-1.0 v4l2src device=/dev/video1 !  
video/x-raw,format=YUY2,width=256,height=384,framerate=25/1 !  
videocrop top=192 ! videoconvert ! videoflip method=clockwise !  
videoconvert ! video/x-raw,format=GRAY8 ! videoconvert ! videoscale !  
waylandsink
```

Thermal Camera (without crop & gray8 convert)



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Fire and Ice



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Thermal Camera UART (57600 baud)

```
U-Boot 2016.11 (Mar 16 2021 - 02:20:19 +0000)
```

```
Sheipa Platform -- Taroko CPU: 500M :rx5281 prid=0xdc02
```

```
DRAM: 64 MiB @ 1066 MHz
```

```
...
```

```
[ 0.000000] Linux version 4.9.51 (root@a239637c8718) (gcc version 6.4.1 20180425 (Realtek RSDK-6.4.1 Build 3029) ) #1 Tue Mar 16 02
```

```
[ 0.000000] MIPS: machine is Sheipa Platform
```

```
[ 0.000000] bootconsole [early0] enabled
```

```
[ 0.000000] CPU0 revision is: 0000dc02 (Taroko)
```

```
[ 0.000000] FPU revision is: 01730001
```

```
[ 0.000000] MIPS: machine is RTS3903N EVB
```

```
...
```

```
.ooooo..o          oooo
d8P'  `Y8          `888
Y88bo.   .oooo.   .oooo.   888
`"Y8888o. d88' `88b `P )88b  888
      `Y88b 888ooo888 .oP"888 888
oo      .d8P 888   .o d8( 888 888
8""88888P'  `Y8bod8P' `Y888""8o o888o
```

```
Please press Enter to activate this console. Build Time: Mar 16 2021 06:37:24
```

Thermal Camera

- ▶ Module is labeled “Infiray Tiny 1B”
- ▶ FW is way more optimized than the i.MX6ULL one
- ▶ Realtek RTS3903N SoC support is fully out of tree
 - ▶ Seems to be mainly used for IP/WLAN cameras
 - ▶ see also <https://drmsamoliu.github.io/hardware.html>
- ▶ Sensor module is quite fragile
 - ▶ I accidentally broke one when doing tests with an oscilloscope
- ▶ I’m focusing on the i.MX6ULL side at least for now

Thermal Camera: Open Issues

- ▶ Figuring out the Vendor Controls
 - ▶ I could extract a bunch of them from the UNI-T binary
 - ▶ “InfiRay P2 Pro” seems to be similar
 - ▶ 0x0bda:0x5830 (P2 Pro) vs 0x0bda:0x3901 (Tiny 1B)
 - ▶ There’s a reverse engineered project for that sensor
 - ▶ <https://github.com/LeoDJ/P2Pro-Viewer/tree/main>
 - ▶ Unfortunately protocol is different (USB request 0x44/0x45 vs 0x20/0x19)

Reverse Engineering

```
thermalcam# mount /dev/mmcblk1p2 /mnt
thermalcam# ls /mnt/root
CalTempConfig.ini      UTi160E_config.ini  gpio_keys_test      power_off
DCIM_100               UTi260B_Thermal     led_ctrl_test       usb_charge_status
ImageCal_config.ini    adc_test            live555MediaServer  uvc-gadget
ImageConfig.ini        cam_test            loop.sh              v4l2tester
SystemConfig.ini       gpio_adc_test       play.png
thermalcam# file /mnt/root/UTi260B_Thermal
/mnt/root/UTi260B_Thermal: ELF 32-bit LSB executable, ARM, EABI5 version 1 (SYSV),
dynamically linked, interpreter /lib/ld-linux.so.3, for GNU/Linux 2.6.31, not stripped
```

- ▶ not easily possible: run binary from mainline
- ▶ binary can be analyzed with radare2 and/or Ghidra
- ▶ static strace binary from original system

Upstream Thermal Camera Handling

- ▶ Figuring out a good way to handle this in Linux
 - ▶ Handle custom vendor control messages via quirk in UVC kernel driver?
 - ▶ How to expose the controls?
 - ▶ Handle everything in userspace?

Questions?

- ▶ Kernel Tree: `git.kernel.org: sre/linux-misc.git` (branch: `uti260b`)

Bonus: Flat Connector to Camera Module

- ▶ 2x20 flat connector to sensor board, pin 1 is marked, top view

| | | | |
|-------------|----|----|----------------------------|
| GND | 1 | 2 | 3V3 |
| 3V3 | 3 | 4 | 3V3 |
| GND | 5 | 6 | 5V0 |
| LED_EN | 7 | 8 | GND |
| GC0308.SCL | 9 | 10 | GC0308.SDA |
| GND | 11 | 12 | -- LOW -- |
| -- LOW -- | 13 | 14 | THERM ~RST |
| GND | 15 | 16 | THERM USB |
| THERM USB | 17 | 18 | GND |
| -- LOW -- | 19 | 20 | GND |
| GC0308.DATA | 21 | 22 | GC0308.DATA |
| GC0308.DATA | 23 | 24 | GC0308.DATA |
| GC0308.DATA | 25 | 26 | GC0308.DATA |
| GC0308.DATA | 27 | 28 | GC0308.DATA |
| GND | 29 | 30 | GC0308.HSYNC (?) (7.5 KHz) |
| -- HIGH -- | 31 | 32 | GND |
| GC0308.PCLK | 33 | 34 | GC0308.INCLK |
| GND | 35 | 36 | GC0308.~RST |
| GC0308.PWDN | 37 | 38 | GND |
| -- LOW -- | 39 | 40 | GND |

Bonus: Enable USB Gadget Mode

```
#!/bin/sh
mkdir -p /sys/kernel/config/usb_gadget/g1
cd /sys/kernel/config/usb_gadget/g1

echo "0x1d6b" > idVendor      # The Linux Foundation
echo "0x0104" > idProduct    # Multifunction Composite Gadget

mkdir -p strings/0x409      # 0x409 = en-US
echo "0000" > strings/0x409/serialnumber
echo "UNI-T" > strings/0x409/manufacturer
echo "UTi260B" > strings/0x409/product

mkdir -p functions/ecm.usb0

# MAC seen by host system
echo "00:00:00:00:00:42" > functions/ecm.usb0/host_addr

mkdir -p configs/c.1
mkdir -p configs/c.1/strings/0x409
echo "UTi260B ECM" > configs/c.1/strings/0x409/configuration

ln -s functions/ecm.usb0 configs/c.1

echo ci_hdrc.0 > /sys/kernel/config/usb_gadget/g1/UDC
```